

第八章 近似方法

1. 定态微扰论 (不含时) 求H的特征态

$H = H_0 + \hat{V}$ 要求划分: ① H_0 简单可解 $H_0 |\psi_n^{(0)}\rangle = E_n^{(0)} |\psi_n^{(0)}\rangle$
 (或前一级算过) ② $\langle \hat{V} \rangle \ll \langle \hat{H}_0 \rangle$

思路: $|\psi_n^{(0)}\rangle \xrightarrow{\hat{V}} |\psi_n\rangle = \sum_l C_l |\psi_l^{(0)}\rangle$

$E_n^{(0)} \xrightarrow{\hat{V}} E_n$

a. 非简并微扰论

$\hat{H} = \hat{H}_0 + \lambda \hat{V} \quad \lambda \ll 1$

$\Rightarrow E_k = E_k^{(0)} + \lambda E_k^{(1)} + \lambda^2 E_k^{(2)} + \dots$ ps: λ 依序作为标记.

$|\psi_k\rangle = |\psi_k^{(0)}\rangle + \lambda |\psi_k^{(1)}\rangle + \lambda^2 |\psi_k^{(2)}\rangle + \dots$

由 $\hat{H} |\psi_k\rangle = E_k |\psi_k\rangle$

λ 的 0 次项: $H_0 |\psi_k^{(0)}\rangle = E_k^{(0)} |\psi_k^{(0)}\rangle$

λ 的 1 次项: $H_0 |\psi_k^{(1)}\rangle + \hat{V} |\psi_k^{(0)}\rangle = E_k^{(1)} |\psi_k^{(1)}\rangle + E_k^{(0)} |\psi_k^{(1)}\rangle$

λ 的 2 次项: $H_0 |\psi_k^{(2)}\rangle + \hat{V} |\psi_k^{(1)}\rangle = E_k^{(2)} |\psi_k^{(2)}\rangle + E_k^{(1)} |\psi_k^{(2)}\rangle + E_k^{(0)} |\psi_k^{(2)}\rangle$

取 λ 的 1 次项, 左边作用 $\langle \psi_m^{(0)} |$, 记 $|\psi_k^{(1)}\rangle = \sum_n C_{kn}^{(1)} |\psi_n^{(0)}\rangle$ (ps: $C_n^{(1)}$ 默认是 $C_{nk}^{(1)}$)

$\Rightarrow E_m^{(0)} C_{km}^{(1)} + V_{mk} = E_k^{(1)} C_{km}^{(1)} + E_k^{(0)} \delta_{mk}$

$\langle \psi_m^{(0)} | \hat{V} | \psi_k^{(0)} \rangle$

$m=k$ 时: $E_k^{(1)} = V_{kk}$

$m \neq k$ 时: $C_{km}^{(1)} = \frac{V_{mk}}{E_k^{(0)} - E_m^{(0)}} \leftarrow$ 这个地方容易反 $\langle \psi_m^{(1)} | \psi_n^{(1)} \rangle = 0$

$\Rightarrow \left\{ \begin{array}{l} E_k \approx E_k^{(0)} + V_{kk} \quad \text{能级的一级近似} \\ |\psi_k\rangle \approx |\psi_k^{(0)}\rangle + \sum_{m \neq k} \frac{V_{mk}}{E_k^{(0)} - E_m^{(0)}} |\psi_m^{(0)}\rangle \quad \text{态的一级近似} \end{array} \right.$ (注意 $m \neq k$, 即一级修正项是 $|\psi_m^{(0)}\rangle$ 垂直方向的态)

* λ 的 2 级近似 ($z=1+1$)

$H_0 |\psi_k^{(2)}\rangle + \hat{V} |\psi_k^{(1)}\rangle = E_k^{(2)} |\psi_k^{(2)}\rangle + E_k^{(1)} |\psi_k^{(2)}\rangle + E_k^{(0)} |\psi_k^{(2)}\rangle$

记 $|\psi_k^{(2)}\rangle = \sum_n C_{kn}^{(2)} |\psi_n^{(0)}\rangle$

$\Rightarrow H_0 \sum_n C_{kn}^{(2)} |\psi_n^{(0)}\rangle + \hat{V} \sum_{m \neq k} \frac{V_{mk}}{E_k^{(0)} - E_m^{(0)}} |\psi_m^{(0)}\rangle = E_k^{(2)} \sum_n C_{kn}^{(2)} |\psi_n^{(0)}\rangle + V_{kk} \sum_{m \neq k} \frac{V_{mk}}{E_k^{(0)} - E_m^{(0)}} |\psi_m^{(0)}\rangle + E_k^{(1)} \sum_n C_{kn}^{(2)} |\psi_n^{(0)}\rangle$

左乘 $\langle \psi_m^{(0)} |$:

$\Rightarrow E_m^{(0)} C_{km}^{(2)} + \sum_{n \neq k} \frac{V_{mn} V_{nk}}{E_k^{(0)} - E_n^{(0)}} = E_k^{(2)} C_{km}^{(2)} + \frac{V_{kk} V_{mk}}{E_k^{(0)} - E_m^{(0)}} (1 - \delta_{mk}) + E_k^{(1)} \delta_{mk}$

$m=k$ 时: $E_k^{(2)} = \sum_{n \neq k} \frac{|V_{nk}|^2}{E_k^{(0)} - E_n^{(0)}}$

n ≠ k 时: $C_m^{(2)} = \frac{1}{E_k^{(0)} - E_m^{(0)}} \left(\sum_{n \neq k} \frac{V_{mn} V_{nk}}{E_k^{(0)} - E_n^{(0)}} - \frac{V_{kk} V_{kk}}{E_k^{(0)} - E_m^{(0)}} \right)$

⇒
$$\begin{cases} E_k \approx E_k^{(0)} + V_{kk} + \sum_{n \neq k} \frac{|V_{nk}|^2}{E_k^{(0)} - E_n^{(0)}} \\ |\psi_k\rangle \approx |\psi_k^{(0)}\rangle + \sum_{n \neq k} \frac{V_{nk}}{E_k^{(0)} - E_n^{(0)}} |\psi_n^{(0)}\rangle \end{cases}$$
 (一阶微扰是标量项, 二阶微扰是耦合项参与)

$|\psi_k\rangle = |\psi_k^{(0)}\rangle + \sum_{n \neq k} \frac{V_{nk}}{E_k^{(0)} - E_n^{(0)}} |\psi_n^{(0)}\rangle + \sum_{m \neq k} \frac{1}{E_k^{(0)} - E_m^{(0)}} \left(\sum_{n \neq k} \frac{V_{mn} V_{nk}}{E_k^{(0)} - E_n^{(0)}} - \frac{V_{kk} V_{kk}}{E_k^{(0)} - E_m^{(0)}} \right) |\psi_m^{(0)}\rangle$

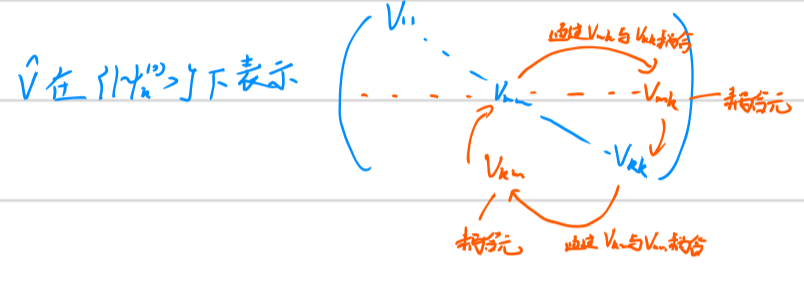
讨论:

i) 正交归一完备性 (仅一级近似)

$\langle \psi_m | \psi_k \rangle = \delta_{m,k} + \sum_{n \neq k} \frac{V_{kn} V_{nk}}{(E_k^{(0)} - E_n^{(0)})(E_l^{(0)} + E_n^{(0)})}$

⇒ $\sum_n |\psi_n\rangle \langle \psi_n| = \hat{I} + O(\lambda^2)$

ii) 图像理解



iii) 简并?



态在非简并元上, 可以正常代公式
若在非简并元上, 则要用到后面的方法.

例: $A = \frac{p^2}{2m} + \frac{1}{2} m \omega^2 X^2 + \frac{1}{2} m \omega^2 \lambda^2 X^2$

求能量本征值精确到 ϵ 二阶小量

$E_n^{(0)} = (n + \frac{1}{2}) \hbar \omega$ $|\psi_n^{(0)}\rangle = |n\rangle$

$E_n \approx E_n^{(0)} + \langle n | \hat{V} | n \rangle + \sum_{k \neq n} \frac{|V_{nk}|^2}{E_n^{(0)} - E_k^{(0)}}$

由 $\langle m | X^2 | n \rangle = \frac{\hbar}{2m\omega} (\sqrt{n(n-1)} \delta_{m,n-2} + \sqrt{(n+1)(n+2)} \delta_{m,n+2} + (n+1) \delta_{m,n} + n \delta_{m,n})$

⇒ $V_{nn} = \frac{\hbar}{4} (2n+1) \hbar \omega \epsilon$

$V_{kn} = \frac{\hbar}{4} \hbar \omega \epsilon (\sqrt{n(n-1)} \delta_{k,n-2} + \sqrt{(n+1)(n+2)} \delta_{k,n+2})$

⇒ $E_n \approx (n + \frac{1}{2}) \hbar \omega + \frac{\hbar}{4} (2n+1) \hbar \omega \epsilon - \frac{1}{32} \hbar \omega \epsilon^2 (n+2)(n+1) + \frac{1}{32} \hbar \omega \epsilon^2 n(n-1)$

$|\psi_n\rangle \approx |n\rangle + \frac{\hbar \omega \epsilon}{8} (\sqrt{n(n-1)} |n-2\rangle - \sqrt{(n+1)(n+2)} |n+2\rangle)$

特殊情况: $E_0 = \frac{1}{2} \hbar \omega + \frac{1}{4} \hbar \omega \epsilon - \frac{1}{16} \hbar \omega \epsilon^2$

$|\psi_0\rangle = |0\rangle - \frac{\sqrt{2}}{8} \epsilon |2\rangle$

精确解: $E_n = (n + \frac{1}{2}) \sqrt{1 + \epsilon} \hbar \omega = (n + \frac{1}{2}) \hbar \omega (1 + \frac{\epsilon}{2} - \frac{\epsilon^2}{8} + \dots)$

b. 简并微扰论

\hat{H}_0 的本征态设为 $\{|\psi_{mp}^{(0)}\rangle, |\psi_{nq}^{(0)}\rangle\}$ ($m \neq n, p, q$ 构成一个简并子空间).

$$\begin{cases} \hat{H}_0 |\psi_{mp}^{(0)}\rangle = E_m^{(0)} |\psi_{mp}^{(0)}\rangle \\ \hat{H}_0 |\psi_{nq}^{(0)}\rangle = E_n^{(0)} |\psi_{nq}^{(0)}\rangle \end{cases}$$

设 $|\psi\rangle = |\psi^{(0)}\rangle + |\psi^{(1)}\rangle$
 $E_n = E_n^{(0)} + E_n^{(1)}$

且设 $|\psi_n^{(1)}\rangle$ 与简并子空间正交
 $|\psi_n^{(0)}\rangle$ 可用简并子空间基 $|\psi_{np}^{(0)}\rangle$ 展开 \Rightarrow $|\psi_n^{(0)}\rangle = \sum_p C_{np}^{(0)} |\psi_{np}^{(0)}\rangle$
 $|\psi_n^{(1)}\rangle = \sum_{p \neq n} C_{np}^{(1)} |\psi_{np}^{(0)}\rangle$

λ 的一次近似表达式

$$\hat{H}_0 |\psi_n^{(1)}\rangle + \hat{V} \sum_p C_{np}^{(0)} |\psi_{np}^{(0)}\rangle = E_n^{(1)} |\psi_n^{(1)}\rangle + E_n^{(0)} \sum_p C_{np}^{(0)} |\psi_{np}^{(0)}\rangle$$

左乘 $\langle \psi_m^{(0)} |$:

$$\sum_p V_{m,n,p} C_{np}^{(0)} = E_n^{(1)} C_{m,n}^{(0)} \Rightarrow \sum_p (V_{m,n,p} - E_n^{(1)} \delta_{p,n}) C_{np}^{(0)} = 0 \quad (E_n^{(1)} \text{ 与 } 0 \text{ 级波函数绑定得内})$$

$$(V) (C_{np}^{(0)}) = E_n^{(1)} (C_{np}^{(0)})$$

即在 $\{|\psi_{mn}^{(0)}\rangle\}$ 下, 在 \hat{H}_0 的简并子空间里对角化 \hat{V}
 (有点像力学完备基那一套, $[\hat{H}_0, \hat{V}] = 0$)
 本征值: 能量的一级微扰
 本征态: 简并子空间内新的 0 级波函数

如简并已消除, 则可以继续利用非简并微扰论求高阶修正 ($|\psi^{(0)}\rangle$ 已经得到)

否则, 需要选择新的 0 级波函数 (无论如何, 根本原则是简并空间中的态不可以有耦合项, 如果有必须引角化)

例: $\hat{H} = \begin{pmatrix} E_1 & \epsilon_1 & \epsilon_2 \\ \epsilon_1 & E_1 & \\ \epsilon_2 & & E_2 \end{pmatrix}$ $\epsilon_1, \epsilon_2 \ll E_1, E_2$
 $\{|0\rangle, |\beta\rangle, |\gamma\rangle\}$

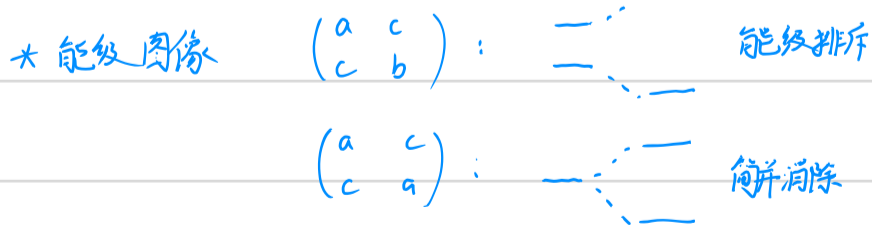
简并子空间 $\begin{pmatrix} \epsilon_1 & \epsilon_1 \\ \epsilon_1 & \epsilon_1 \end{pmatrix} \Rightarrow \begin{cases} \pm \epsilon_1 \\ \frac{\sqrt{2}}{2} (|0\rangle \pm |\beta\rangle) \end{cases} \equiv |\pm\rangle$

\Rightarrow 1 级能量修正 $E_{\pm} \approx E_1$

新的零级波函数 $\{| \pm \rangle, |\gamma\rangle\}$

$\Rightarrow \langle + | \gamma \rangle = \frac{\sqrt{2}}{2} \epsilon_2 \quad \langle - | \gamma \rangle = \frac{\sqrt{2}}{2} \epsilon_2$

新矩阵表示: $\begin{pmatrix} E_1 + \epsilon_1 & \frac{\sqrt{2}}{2} \epsilon_1 \\ \frac{\sqrt{2}}{2} \epsilon_1 & E_1 - \epsilon_1 \\ \frac{\sqrt{2}}{2} \epsilon_2 & \frac{\sqrt{2}}{2} \epsilon_2 & E_2 \end{pmatrix} \Rightarrow$ 2 阶: $E_1 + \epsilon_1 + \frac{\frac{1}{2} \epsilon_2^2}{E_1 - \epsilon_1 - E_2}$ (本来就是 $\frac{\frac{1}{2} \epsilon_2^2}{E_1 - E_2}$)
 $E_1 - \epsilon_1 + \frac{\frac{1}{2} \epsilon_2^2}{E_1 - \epsilon_1 - E_2}$ (结果和非简并一样)
 $E_2 + \frac{\frac{1}{2} \epsilon_2^2}{E_2 - (E_1 + \epsilon_1)} + \frac{\frac{1}{2} \epsilon_2^2}{E_2 - (E_1 - \epsilon_1)} = E_2 + \frac{E_2^2}{E_2 - E_1}$

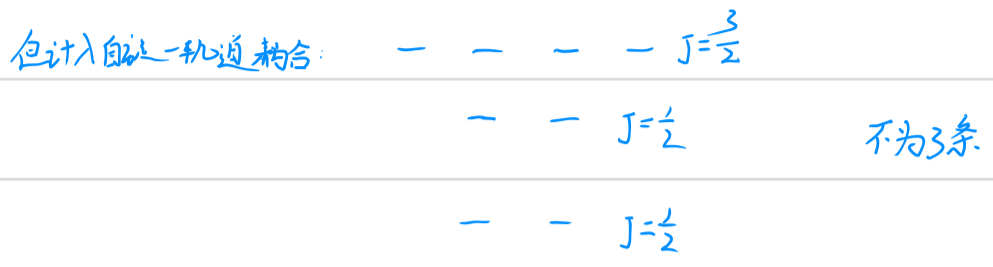
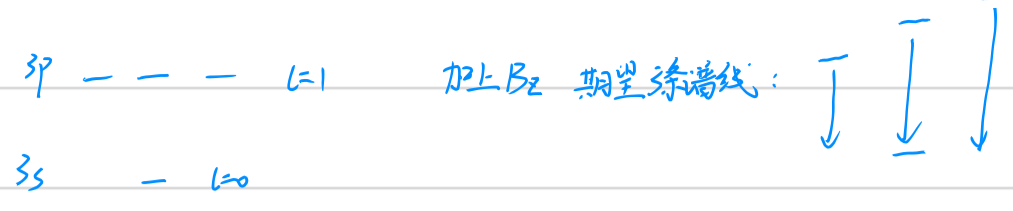


PS: 若 $E_1 \approx E_2$, 则是近简并情况, 需要对整个 \hat{V} 尝试对角化

* "实际" 方法

寻找算符 \hat{A} , 使 $[\hat{H}_0, \hat{A}] = 0$, $[\hat{V}, \hat{A}] = 0$, 且 (\hat{H}_0, \hat{A}) 的共同本征态在 \hat{H}_0 的简并子空间中无简并, 则这些本征态为好的零级波函数

例: 反常 Zeeman 效应 (^{23}Na)

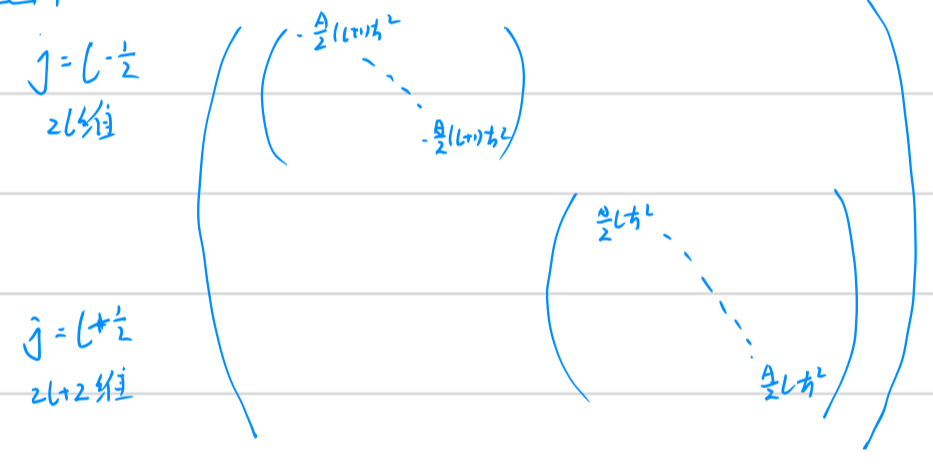


$\hat{H} = A \vec{L} \cdot \vec{S} + B(L_z^2 + 2S_z^2)$ (假设已处理 Hamiltonian 其它的部分)

$\textcircled{1} A \gg B \quad \hat{H}_0 = A \vec{L} \cdot \vec{S} \quad \hat{V} = B(L_z^2 + 2S_z^2)$
 $\frac{j^2 - l^2 - s^2}{2}$

选取基为 $|\vec{l}^2, J_z\rangle \rightarrow |j, m_j\rangle$

H_0 矩阵:



$i) E_0 = \langle j, m_j | \hat{H}_0 | j, m_j \rangle = \frac{A}{2} [j(j+1) - l(l+1) - s(s+1)] \hbar^2$
 $\Rightarrow \begin{cases} s=\frac{1}{2} \quad j=l+\frac{1}{2} & E_0 = \frac{A}{2} \hbar^2 \\ s=\frac{1}{2} \quad j=l-\frac{1}{2} & E_0 = -\frac{A}{2} (l+1) \hbar^2 \end{cases}$

$ii) \langle j', m_j' | \hat{V} | j, m_j \rangle = B \langle j', m_j' | J_z^2 | j, m_j \rangle + B \langle j', m_j' | S_z^2 | j, m_j \rangle$
 $= B m_j' \hbar \delta_{j'j} \delta_{m_j'm_j} + B \langle j', m_j' | S_z^2 | j, m_j \rangle$
 $\Rightarrow \begin{cases} j=l+\frac{1}{2}: \langle j, m_j | S_z^2 | j, m_j \rangle = \frac{1}{2} \hbar^2 (\frac{j+m_j}{j} - \frac{j-m_j}{j}) \delta_{m_j, m_j} = \frac{m_j}{j} \hbar^2 \delta_{m_j, m_j} \text{ (只有)} \\ j=l-\frac{1}{2}: \langle j, m_j | S_z^2 | j, m_j \rangle = -\frac{m_j}{2(j+1)} \hbar^2 \delta_{m_j, m_j} \end{cases}$

$iii) \text{非对角元}$
 $\langle j', m_j' | J_z^2 | j, m_j \rangle = 0$ (正交)
 $\langle j', m_j' | S_z^2 | j, m_j \rangle = \frac{j=l-\frac{1}{2}}{j=l+\frac{1}{2}} \left(-\frac{1}{2} \sqrt{\frac{j+m_j+1}{2j+2}} \sqrt{\frac{j-m_j}{2j}} - \frac{1}{2} \sqrt{\frac{j-m_j+1}{2j+2}} \sqrt{\frac{j+m_j}{2j}} \right) \delta_{m_j', m_j}$

$1 + \frac{j(j+1) - l(l+1) + s(s+1)}{2j(j+1)}$
 Lande 因子

\Rightarrow 简并微扰 (一级)

$j=l+\frac{1}{2}: E_0 + E_1 = \frac{A}{2} \hbar^2 + B \left(m_j + \frac{m_j}{2j} \right) \hbar$
 $j=l-\frac{1}{2}: E_0 + E_1 = -\frac{A}{2} (l+1) \hbar^2 + B \left(m_j - \frac{m_j}{2(j+1)} \right) \hbar$

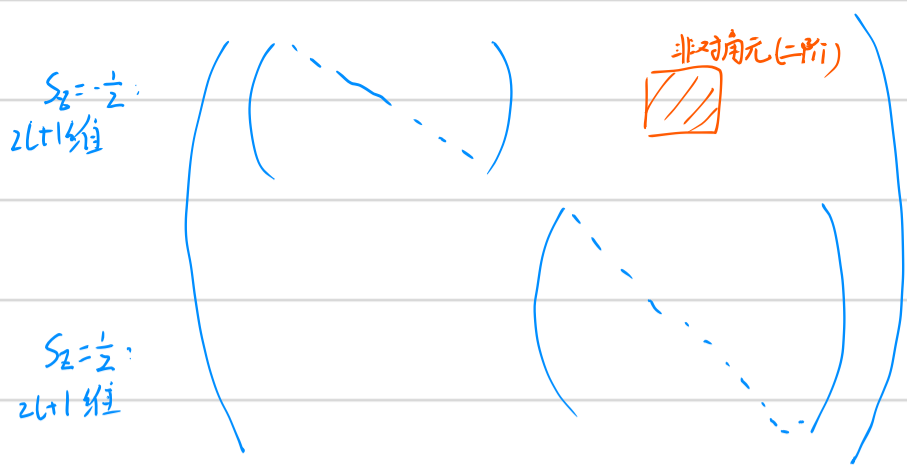
PS: $[\hat{H}_0, \hat{J}_z] = 0 \quad [\hat{V}, \hat{J}_z] = 0 \rightarrow \{ \hat{J}_z, \hat{J}^2 \}$ 好!
 $[\hat{H}_0, \hat{J}^2] = 0 \quad [\hat{V}, \hat{J}^2] \neq 0$
 (但只选 J_z)

$\textcircled{2} A \ll B$

$\hat{H}_0 = B(L_z^2 + 2S_z^2)$ 零级: $\{ |m_L, S_z\rangle \}$ $E_0 = (m_L + 2m_S) B \hbar$

$\hat{V} = A \vec{L} \cdot \vec{S}$

$\langle m_L' S_z' | \hat{V} | m_L S_z \rangle = A \langle m_L' S_z' | [L_z^2 S_z^2 + \frac{1}{2} (L^2 S^2 + L \cdot S)] | m_L S_z \rangle$
 $= A (m_L S_z \hbar^2 \delta_{m_L, m_L'} \delta_{S_z, S_z'} + \text{非对角元} \delta_{S_z', S_z-1} \delta_{m_L, m_L+1} + \text{非对角元} \delta_{S_z', S_z+1} \delta_{m_L, m_L-1})$ (非对角元: $m_L + S_z = m_L' + S_z'$)

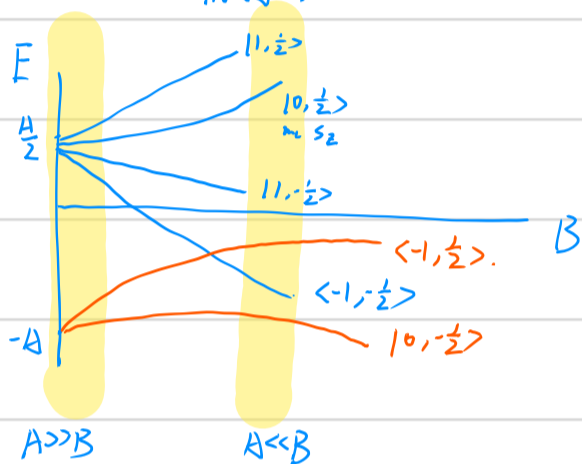


非简并微扰论:

$$E_0 + E_1 = B(m_l + 2S_z)\hbar + A\hbar^2 S_z m_l$$

③ $A \sim B$ 必须整个矩阵统一对角化 ($2 \times (2l+1)$ 矩阵)

相当于 $\hat{V} = A\hat{L} \cdot \hat{S} + B(L_z^2 + 2S_z^2)$ 的简并微扰 (0级为库仑能级)



* 如 \hat{V} 对角化不能消除简并, 即一级近似下能级不分裂, 则必须考虑简并子空间之外的态的影响

$$|\psi\rangle = |\psi^{(0)}\rangle + |\psi^{(1)}\rangle + |\psi^{(2)}\rangle + \dots$$

$$|\psi^{(0)}\rangle = \sum_n C_n^{(0)} |\psi_n^{(0)}\rangle$$

$$|\psi^{(1)}\rangle = \sum_{n \neq m} C_n^{(1)} |\psi_n^{(0)}\rangle$$

$$|\psi^{(2)}\rangle = \sum_{n \neq m} C_n^{(2)} |\psi_n^{(0)}\rangle \quad (|\psi^{(1)}\rangle \text{ 也正交于简并子空间})$$

$$\begin{cases}
 (\hat{H}_0 - E_n^{(0)}) |\psi_n^{(0)}\rangle = 0 & 0 \text{ 次} \\
 (\hat{H}_0 - E_n^{(1)}) |\psi^{(1)}\rangle = (E_n^{(1)} - \hat{V}) |\psi^{(0)}\rangle & 1 \text{ 次} \\
 (\hat{H}_0 - E_n^{(2)}) |\psi^{(2)}\rangle = (E_n^{(2)} - \hat{V}) |\psi^{(1)}\rangle + E_n^{(2)} |\psi^{(0)}\rangle & 2 \text{ 次}
 \end{cases}$$

$\langle \psi_m^{(0)} |$ 左乘 λ 的 1 次项式

$$\sum_n [V_{m0,n} - \delta_{m,n} E_n^{(1)}] C_n^{(1)} = 0$$

如 $V_{m0,m}$ 对角且对角元相等, 则能级在一级近似下依然简并 (对不同态作用效果相同)

$\langle \psi_m^{(0)} |$ 左乘 λ 的 2 次项式

$$E_n^{(2)} C_m^{(0)} = \sum_{n \neq m} V_{m0,n} C_n^{(1)}$$

非对角元

$\langle \psi_n^{(0)} |$ 左乘 λ 的 1 次项式

$$(E_n^{(0)} - E_m^{(0)}) C_n^{(1)} = - \sum_{\mu} V_{n, \mu} C_{\mu}^{(0)}$$

$$\Rightarrow C_n^{(1)} = \sum_{\mu} \frac{V_{n, \mu}}{E_n^{(0)} - E_{\mu}^{(0)}} C_{\mu}^{(0)}$$

可以看到当 $\nu, \mu=1$ 时, 回归非简并微扰论



V^{μ} 矩阵的本征方程, 得到 $C_{\mu}^{(1)}, E_n^{(2)}$

$$\sum_{\mu} \sum_{\nu \neq \mu} \frac{V_{\nu, \nu} V_{\nu, \mu}}{E_{\nu}^{(0)} - E_{\mu}^{(0)}} C_{\mu}^{(0)} = E_n^{(2)} C_{\mu}^{(0)}$$

ν, μ 为自由指标

例: $H = \begin{pmatrix} E_1 & a & \\ & E_1 & b \\ a^* & b^* & E_2 \end{pmatrix}$

(i) 简并子空间 $E^{(1)} = 0$

的求本征问题的解为 $E_1^{(1)} = 0, \frac{|a|^2 + |b|^2}{E_2 - E_1} \Rightarrow \begin{cases} E_1 \\ E_1 + \frac{|a|^2 + |b|^2}{E_2 - E_1} \end{cases}$

$\frac{ab^*}{E_1 - E_2}$ 都是二阶的

(ii) 非简并子空间 $E_2 + \frac{|a|^2 + |b|^2}{E_2 - E_1}$

例: 自旋 $\frac{1}{2}$ 的三维各向同性谐振子, 处于基态. 在微扰 $\hat{V} = \lambda \sigma_z \hat{z}$ 的作用下, 求基态能级准确到二阶基态空间 $\{|n_x, n_y, n_z, \uparrow\rangle, |n_x, n_y, n_z, \downarrow\rangle\}$

二阶基态空间 $\{|n_x, n_y, n_z, \uparrow\rangle, |n_x, n_y, n_z, \downarrow\rangle\}$

$$\hat{z} = \sqrt{\frac{\hbar}{2m\omega}} (\hat{a}^{\dagger} + \hat{a})$$

	$ 0, 0, 0, \uparrow\rangle$	$ 0, 0, 0, \downarrow\rangle$	$ 0, 0, 1, \uparrow\rangle$	$ 0, 0, 1, \downarrow\rangle$	
$\langle 0, 0, 0, \uparrow $	$\begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$		$\frac{\sqrt{5}}{\sqrt{2m\omega}} \lambda$	0	
$\langle 0, 0, 0, \downarrow $			0	$-\frac{\sqrt{5}}{\sqrt{2m\omega}} \lambda$	
$\langle 0, 0, 1, \uparrow $		$\frac{\sqrt{\hbar}}{\sqrt{2m\omega}} \lambda$	0	$\begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$	0
$\langle 0, 0, 1, \downarrow $		0	$-\frac{\sqrt{\hbar}}{\sqrt{2m\omega}} \lambda$		0

E_0 简并微扰: $\begin{pmatrix} -\frac{\lambda^2}{2m\omega^2} & 0 \\ 0 & -\frac{\lambda^2}{2m\omega^2} \end{pmatrix}$ 二阶修正仍简并 $E \approx \frac{3}{2}\hbar\omega - \frac{\lambda^2}{2m\omega^2}$

例: 自旋 $\frac{1}{2}$ 的三维各向同性谐振子, 处于基态. 在微扰 $\hat{V} = \lambda \hat{\sigma}_x \hat{y}^2$ 的作用下, 求基态能级准确到

二阶基态空间 $\{|n_x, n_y, n_z, \uparrow\rangle, |n_x, n_y, n_z, \downarrow\rangle\}$

$$\hat{y}^2 = \frac{\hbar}{2m\omega} (\hat{a}^2 + \hat{a}^{\dagger 2} + 2\hat{a}^{\dagger}\hat{a} + 1)$$

	$ 0, 0, 0, \uparrow\rangle$	$ 0, 0, 0, \downarrow\rangle$	$ 0, 2, 0, \uparrow\rangle$	$ 0, 2, 0, \downarrow\rangle$
$\langle 0, 0, 0, \uparrow $	$\frac{3}{2}\hbar\omega$	$\frac{\hbar}{2m\omega}\lambda$	0	$\frac{\sqrt{2}\hbar}{2m\omega}\lambda$
$\langle 0, 0, 0, \downarrow $	$\frac{\hbar}{2m\omega}\lambda$	$\frac{3}{2}\hbar\omega$	$\frac{\sqrt{2}\hbar}{2m\omega}\lambda$	0
$\langle 0, 2, 0, \uparrow $	0	$\frac{\sqrt{2}\hbar}{2m\omega}\lambda$	$\frac{7}{2}\hbar\omega$	$\frac{\hbar}{2m\omega}\lambda$
$\langle 0, 2, 0, \downarrow $	$\frac{\sqrt{2}\hbar}{2m\omega}\lambda$	0	$\frac{\hbar}{2m\omega}\lambda$	$\frac{7}{2}\hbar\omega$

一阶: $\frac{3}{2}\hbar\omega \pm \frac{\hbar}{2m\omega}\lambda$ 二阶: 对 $\frac{3}{2}\hbar\omega - \frac{\hbar}{2m\omega}\lambda$: $|\psi^{(1)}\rangle = \frac{\sqrt{2}}{2}(|0, 0, 0, \uparrow\rangle - |0, 0, 0, \downarrow\rangle)$

$$E^{(2)} = \frac{|\langle 0, 2, 0, \uparrow|\hat{V}|\psi^{(1)}\rangle|^2 + |\langle 0, 2, 0, \downarrow|\hat{V}|\psi^{(1)}\rangle|^2}{\frac{3}{2}\hbar\omega - \frac{7}{2}\hbar\omega} = -\frac{\hbar\lambda^2}{4m^2\omega^3}$$

$\frac{|\frac{-\sqrt{2}\hbar}{2m\omega}\lambda|^2 + |\frac{\sqrt{2}\hbar}{2m\omega}\lambda|^2}{4\hbar\omega}$

对 $\frac{3}{2}\hbar\omega + \frac{\hbar}{2m\omega}\lambda$: $|\psi^{(1)}\rangle = \frac{\sqrt{2}}{2}(|0, 0, 0, \uparrow\rangle + |0, 0, 0, \downarrow\rangle)$

$$E^{(2)} = -\frac{\hbar\lambda^2}{4m^2\omega^3}$$

d. 微扰论在氢原子中的应用.

零级近似: $H_0 = -\frac{\hbar^2}{2m}\nabla^2 + V(r)$ Coulomb. $\Rightarrow |n, l, m\rangle$

$$E_n = -\left(\frac{m}{2\hbar^2} \left(\frac{e^2}{4\pi\epsilon_0}\right)^2\right) \frac{1}{n^2}$$

$2n^2$ 简并

① 精细结构

i) 相对论修正 $T = \frac{p^2}{2m} \Rightarrow T = \sqrt{p^2 c^2 + m^2 c^4} - mc^2 \approx \frac{p^2}{2m} - \frac{p^4}{8m^3 c^2}$

量子化 $[\hat{p}^4, \hat{L}^2] = [\hat{p}^2, \hat{L}_z] = 0$

$\{\hat{L}^2, \hat{L}_z\}$ $E_r = \langle n, l, m | \frac{-\hat{p}^4}{8m^3 c^2} | n, l, m \rangle = -\frac{E_n^2}{2mc^2} \left(\frac{4n}{l+2} - 3\right)$ $\frac{E_n}{mc^2} \sim 10^{-5}$

(ii) 自旋-轨道耦合

$$\hat{H}_{so} = \frac{e\hbar}{8\pi\epsilon_0} \frac{1}{m^2} \frac{1}{c^2 r^3} \hat{L} \cdot \hat{S}$$

$$[\hat{H}_{so}, \hat{L}^2] = [\hat{H}_{so}, \hat{S}^2] = 0 \quad \text{但} \quad [\hat{H}_{so}, \hat{L}_z] \neq 0 \quad [\hat{H}_{so}, \hat{S}_z] \neq 0$$

$$[\hat{H}_{so}, \hat{J}^2] = 0 \quad [\hat{H}_{so}, \hat{J}_z] = 0 \quad \Rightarrow \text{选择耦合表象}$$

$\{|n, l, s, j, m\rangle\}$

$$E_{so} = \frac{E_n^2}{mc^2} \left\{ \frac{n[j(j+1) - l(l+1) - \frac{3}{4}]}{l(l+\frac{1}{2})(l+1)} \right\}$$

精细结构总影响

$$E_{n,j} = E_n + \frac{E_n^2}{2mc^2} \left(3 - \frac{4n}{j+\frac{1}{2}}\right) = \frac{E_0}{n^2} \left[1 + \frac{\alpha^2}{n^2} \left(\frac{n}{j+\frac{1}{2}} - \frac{3}{4}\right)\right]$$

② Zeeman Effect

③ 超精细结构

核自旋与电子轨道/自旋的相互作用 $\hat{H}_{hf} \propto \vec{I} \cdot \vec{J}$

$l=0$: 定义 $\vec{F} = \vec{I} + \vec{S}$ $[\hat{F}^2, \hat{H}_{hf}] = [\hat{F}_z, \hat{H}_{hf}] = 0$

$|n, l, s, j, I, F, m_f\rangle$ $l=0, s=\frac{1}{2}, I=\frac{1}{2} \Rightarrow F=0, 1$
 $\Rightarrow J=\frac{1}{2}$

$$E_{hf}^{(1)} = \langle n, l, j, s, I, F, m_f | \hat{H}_{hf} | n, l, j, s, I, F, m_f \rangle$$

$$= \frac{1}{2} A [F(F+1) - I(I+1) - S(S+1)] \hbar^2$$

$$= A \hbar^2 \begin{cases} \frac{1}{4} & \text{三重态} \\ -\frac{3}{4} & \text{单态} \end{cases}$$



2. 变分法

对于给定 \hat{H} , 和任意态 $|\psi\rangle$, 均有如下关系

$$\langle \psi | \hat{H} | \psi \rangle \geq E_{gs} \quad \text{基态能量}$$

||
 $\sum_n |c_n|^2 E_n$

PS: 用 $\hat{P} = \hat{I} - |\psi_{min}\rangle \langle \psi_{min}|$

$\hat{H}' = \hat{P} \hat{H} \hat{P}$ 可用变分法求第一激发态

应用: 猜基态的形式, 变成最优化问题

$|\psi(\alpha_n)\rangle$, 其中 α_n 为参数

$$E(\alpha_n) = \frac{\langle \psi(\alpha_n) | \hat{H} | \psi(\alpha_n) \rangle}{\langle \psi(\alpha_n) | \psi(\alpha_n) \rangle} \quad \text{求 } \alpha_n \text{ 使 } E(\alpha_n) \text{ 取极小值} \quad \frac{\partial E(\alpha_n)}{\partial \alpha_n} = 0 \Rightarrow E_{gs} \text{ 近似值}$$

关键: 怎么猜 $|\psi(\alpha_n)\rangle$ 使得子空间离 G_S 足够近?

(成功理论总是做到的)

例: He 原子 (Griffith)

$$H = -\frac{\hbar^2}{2m} (\nabla_1^2 + \nabla_2^2) - \frac{e^2}{4\pi\epsilon_0} \left(\frac{1}{r_1} + \frac{1}{r_2} - \frac{1}{|\vec{r}_1 - \vec{r}_2|}\right) = \underbrace{-\frac{\hbar^2}{2m} (\nabla_1^2 + \nabla_2^2)}_{H_0} - \underbrace{\frac{e^2}{4\pi\epsilon_0} \left(\frac{1}{r_1} + \frac{1}{r_2}\right)}_{H_1} + \underbrace{\frac{e^2}{4\pi\epsilon_0} \left(\frac{1}{|\vec{r}_1 - \vec{r}_2|}\right)}_V$$

由 H 原子波函数 $\langle \vec{r} | n, l, m \rangle = \frac{1}{\sqrt{\pi a^3}} e^{-\frac{r}{a}}$ 启发

设 $\psi(\vec{r}_1, \vec{r}_2) = \frac{z^3}{\pi a^3} e^{-\frac{z(r_1+r_2)}{a}}$ (期待 $z < 2$)

$$\langle H_0 \rangle = 2z^2 E_1$$

$$\langle H_1 \rangle = 2(z-2) \frac{e^2}{4\pi\epsilon_0} \underbrace{\langle \frac{1}{r} \rangle}_{\frac{z}{a}} \Rightarrow \langle H \rangle = \left[-2z^2 + \frac{27}{4}z\right] E_1 \quad \frac{d\langle H \rangle}{dz} = 0 \Rightarrow z \approx \frac{27}{16} \quad \langle H \rangle = \frac{27^2}{16 \times 8} E_1 \approx -77.5 \text{ eV}$$

$$\langle V \rangle = -\frac{5}{4} z E_1$$

(实验上为 -78.98 eV)

3. 含时微扰

a 基本理论 (迭代形式)

跃迁的解算 $|\psi_n\rangle \rightarrow |\psi\rangle \quad \hat{H}_0|\psi_n\rangle = E_n|\psi_n\rangle$

$$\hat{H} = \hat{H}_0 + \hat{V}(t) \quad \text{含时微扰项}$$

设 $|\psi\rangle = \sum_n C_n(t) |\psi_n\rangle$, 代入 $i\hbar \frac{d}{dt} |\psi\rangle = (\hat{H}_0 + \hat{V}) |\psi\rangle$

$$\Rightarrow i\hbar \frac{\partial}{\partial t} C_m(t) = E_m C_m(t) + \sum_n V_{mn}(t) C_n(t) \quad \text{矩阵形式: } i\hbar \frac{\partial}{\partial t} \begin{pmatrix} C_m \end{pmatrix} = \begin{pmatrix} E_1 & & \\ & \ddots & \\ & & E_n \end{pmatrix} \begin{pmatrix} C_m \end{pmatrix} + \begin{pmatrix} V_{m1} \\ \vdots \\ V_{mn} \end{pmatrix} \begin{pmatrix} C_m \end{pmatrix}$$

作变换 $\tilde{C}_n(t) = e^{i\frac{E_n t}{\hbar}} C_n(t) \Rightarrow i\hbar \frac{\partial}{\partial t} \tilde{C}_n(t) = -E_n \tilde{C}_n(t) + e^{i\frac{E_n t}{\hbar}} i\hbar \frac{\partial}{\partial t} C_n(t)$

$$\Rightarrow i\hbar \frac{\partial}{\partial t} \tilde{C}_m(t) = \sum_n V_{mn}(t) e^{i\frac{(E_m - E_n)t}{\hbar}} \tilde{C}_n(t) \quad \text{定义 } \omega_{mn} = (E_m - E_n)/\hbar$$

$$\Rightarrow i\hbar \frac{\partial}{\partial t} \tilde{C}_m(t) = \sum_n V_{mn}(t) e^{i\omega_{mn}t} \tilde{C}_n(t) \quad \text{(相互作用绘景)}$$

↑
由 V_{mn} 说明是 n -阶

rotating frame

迭代微扰:

i) $t=0$ 时的初态为零级近似

ii) 零级近似代入上式右边 \Rightarrow 一级修正

iii) 反复迭代求更高阶修正

例: 二能级系统 $|\psi\rangle = \begin{pmatrix} C_a \\ C_b \end{pmatrix}$

$$i\hbar \frac{\partial}{\partial t} \tilde{C}_a = V_{aa} \tilde{C}_a + V_{ab} e^{i\omega_{ab}t} \tilde{C}_b$$

$$i\hbar \frac{\partial}{\partial t} \tilde{C}_b = V_{bb} \tilde{C}_b + V_{ba} e^{i\omega_{ba}t} \tilde{C}_a$$

$$i\hbar \frac{\partial}{\partial t} \begin{pmatrix} \tilde{C}_a \\ \tilde{C}_b \end{pmatrix} = \begin{pmatrix} V_{aa} & V_{ab} e^{i\omega_{ab}t} \\ V_{ba} e^{i\omega_{ba}t} & V_{bb} \end{pmatrix} \begin{pmatrix} \tilde{C}_a \\ \tilde{C}_b \end{pmatrix}$$

设 $\tilde{C}_a(0) = 1 \quad \tilde{C}_b(0) = 0$ 零级 $(C_a(0) = e^{-i\frac{E_a t}{\hbar}} \quad C_b(0) = 0)$

一级修正

$$\begin{cases} i\hbar \frac{\partial}{\partial t} \tilde{C}_a^{(1)} = V_{aa} \tilde{C}_a^{(1)} \\ i\hbar \frac{\partial}{\partial t} \tilde{C}_b^{(1)} = V_{ba} e^{i\omega_{ba}t} \tilde{C}_a^{(1)} \end{cases} \Rightarrow \begin{cases} \tilde{C}_a^{(1)} = -\frac{i}{\hbar} \int_0^t V_{aa}(t') dt' \\ \tilde{C}_b^{(1)} = -\frac{i}{\hbar} \int_0^t V_{ba}(t') e^{i\omega_{ba}t'} dt' \end{cases}$$

二级修正:

$$i\hbar \frac{\partial}{\partial t} \tilde{C}_a^{(2)} = V_{aa} \tilde{C}_a^{(2)} + V_{ab} e^{i\omega_{ab}t} \tilde{C}_b^{(1)}$$

$$\Rightarrow \tilde{C}_a^{(2)} = \dots$$

\Rightarrow 准确到一级修正:

$$\begin{cases} \tilde{C}_a(t) = 1 - \left(\frac{i}{\hbar}\right) \int_0^t V_{aa}(t') dt' + o(V^2) \\ \tilde{C}_b(t) = -\left(\frac{i}{\hbar}\right) \int_0^t V_{ba}(t') e^{i\omega_{ba}t'} dt' + o(V^2) \end{cases} \quad |\tilde{C}_a|^2 + |\tilde{C}_b|^2 = 1 + o(V^2)$$

也可以设 $\begin{cases} d_a = e^{\frac{i}{\hbar} \int_0^t V_{aa}(t') dt'} \tilde{C}_a \\ d_b = e^{\frac{i}{\hbar} \int_0^t V_{bb}(t') dt'} \tilde{C}_b \end{cases} \rightarrow$ 正则形式 \checkmark

b. 跃迁

薛定谔方程 $i\hbar \frac{\partial}{\partial t} \tilde{C}_n = \sum_m V_{nm} \tilde{C}_m e^{i\omega_{nm}t}$

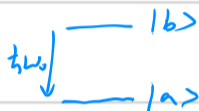
设初态为 k 态 $\tilde{C}_n = \delta_{nk}$

一级含时微扰为 $i\hbar \frac{\partial}{\partial t} \tilde{C}_m^{(1)} = V_{mk} e^{i\omega_{mk}t} \Rightarrow \tilde{C}_m^{(1)} = -\frac{i}{\hbar} \int_0^t V_{mk}(t') e^{i\omega_{mk}t'} dt'$

$\Rightarrow \tilde{C}_n = \delta_{nk} - \frac{i}{\hbar} \int_0^t V_{nk}(t') e^{i\omega_{nk}t'} dt'$

对于 $m \rightarrow k$, 跃迁概率

$P_{k \rightarrow m}(t) = \frac{1}{\hbar^2} \left| \int_0^t V_{mk}(t') e^{i\omega_{mk}t'} dt' \right|^2 \quad (m \neq k)$

例: 光场与二能级原子的耦合 $E_b - E_a = \hbar\omega_0$ 

$V(t) = V(\vec{r}) (e^{i\omega t} + e^{-i\omega t})$

i) $\langle a | V(\vec{r}) | b \rangle = V_{ab}$ $V_{aa} = V_{bb} = 0$. 初态为 $|a\rangle$

$\tilde{C}_b(t) = -\frac{i}{\hbar} \int_0^t V_{ba} (e^{i\omega t'} + e^{-i\omega t'}) e^{i\omega_0 t'} dt' = -\frac{V_{ba}}{\hbar} \left[\frac{e^{i(\omega_0 + \omega)t} - 1}{\omega_0 + \omega} + \frac{e^{i(\omega_0 - \omega)t} - 1}{\omega_0 - \omega} \right]$

跃迁几率: $P_{a \rightarrow b}(t) = |\tilde{C}_b|^2$

rotating-wave approximate (RWA): (将快速振荡项扔了)

当 $\omega_0 \approx \omega$ 且 $V_{ab} \ll \hbar\omega_0, \hbar\omega$ 时, $\frac{e^{i(\omega_0 + \omega)t} - 1}{\omega_0 + \omega}$ 可忽略

$\tilde{C}_b(t) \approx -\frac{V_{ba}}{\hbar} \frac{e^{i(\omega_0 - \omega)t} - 1}{\omega_0 - \omega} = -\frac{V_{ba}}{\hbar} e^{i(\omega_0 - \omega)\frac{t}{2}} \frac{1}{\omega_0 - \omega} 2i \sin\left[\frac{\omega_0 - \omega}{2}t\right]$

$\Rightarrow P_{a \rightarrow b}(t) = \frac{4|V_{ab}|^2}{\hbar^2} \frac{\sin^2\left[\frac{(\omega_0 - \omega)t}{2}\right]}{(\omega_0 - \omega)^2}$ 由 $\lim_{t \rightarrow \infty} \frac{\sin^2\left[\frac{(\omega_0 - \omega)t}{2}\right]}{(\omega_0 - \omega)^2} = \frac{\pi}{4} t \delta\left(\frac{\omega_0 - \omega}{2}\right)$ ($\lim_{\delta \rightarrow \infty} \frac{\sin^2 \delta x}{\delta x^2} = \pi \delta(x)$)

$P_{a \rightarrow b}(t) \xrightarrow{t \rightarrow \infty} \frac{2\pi}{\hbar^2} t |V_{ab}|^2 \delta(\omega_0 - \omega)$ 作图

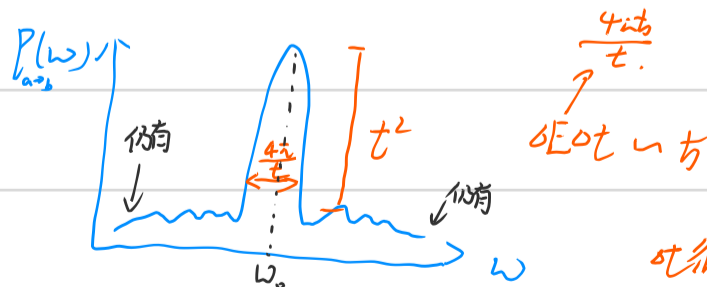
单位时间跃迁速率: $\omega_{a \rightarrow b} = \frac{2\pi}{\hbar} |V_{ab}|^2 \delta(\omega_0 - \omega)$

如 $|b\rangle$ 附近有很多态

$\sum_b P_{a \rightarrow b}(t) \Big|_{t \rightarrow \infty} = \int dE \underbrace{L(E)}_{\text{态密度}} \frac{2\pi}{\hbar} |V_{ab}|^2 \delta(E - E_b) t$

$\bar{\omega} = L(E_b) \frac{2\pi}{\hbar} |V_{ab}|^2$

PS: 上面讨论 t 不能太大: $t \ll \frac{1}{|V_{ab}|}, \frac{1}{|\omega_0 - \omega|}$ (防止展宽)



t 很小时, 跃迁可以
不守恒 (i.e. 微扰)

ii) 严格解 (Rabi) under RWA

$i\hbar \frac{\partial}{\partial t} \begin{pmatrix} C_a \\ C_b \end{pmatrix} = \begin{pmatrix} E_a & V_{ab}(e^{i\omega t} + e^{-i\omega t}) \\ V_{ba}(e^{i\omega t} + e^{-i\omega t}) & E_b \end{pmatrix} \begin{pmatrix} C_a \\ C_b \end{pmatrix}$

rotating frame:
$$\begin{cases} \tilde{C}_a = C_a e^{i(\frac{E_a + E_b}{2\hbar} - \frac{\omega}{2})t} \\ \tilde{C}_b = C_b e^{i(\frac{E_a + E_b}{2\hbar} + \frac{\omega}{2})t} \end{cases} \Rightarrow i\frac{\partial}{\partial t} \begin{pmatrix} \tilde{C}_a \\ \tilde{C}_b \end{pmatrix} = \begin{pmatrix} \frac{\delta}{2} & \frac{V_{ab}}{\hbar} (1 + e^{-i2\omega t}) \\ \frac{V_{ba}}{\hbar} (1 + e^{i2\omega t}) & -\frac{\delta}{2} \end{pmatrix} \begin{pmatrix} \tilde{C}_a \\ \tilde{C}_b \end{pmatrix}$$

(其中 $\delta = \omega - \omega_0$) 失谐 $\begin{cases} \delta < 0 & \text{红} \\ \delta > 0 & \text{蓝} \end{cases}$

RWA:
$$i\frac{\partial}{\partial t} \begin{pmatrix} \tilde{C}_a \\ \tilde{C}_b \end{pmatrix} = \begin{pmatrix} \frac{\delta}{2} & \frac{V_{ab}}{\hbar} \\ \frac{V_{ba}}{\hbar} & -\frac{\delta}{2} \end{pmatrix} \begin{pmatrix} \tilde{C}_a \\ \tilde{C}_b \end{pmatrix} \Rightarrow \tilde{V} = \frac{\delta}{2}\sigma_z + \text{Re}(\frac{V_{ab}}{\hbar})\sigma_x - \text{Im}(\frac{V_{ab}}{\hbar})\sigma_y$$

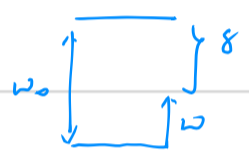
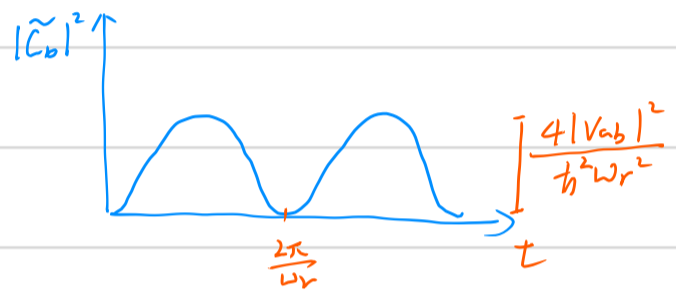
(不全对)

$$\begin{pmatrix} \tilde{C}_a(t) \\ \tilde{C}_b(t) \end{pmatrix} = e^{-i\tilde{V}t} \begin{pmatrix} \tilde{C}_a(0) \\ \tilde{C}_b(0) \end{pmatrix}$$

由 $e^{-i\psi\vec{\sigma}\cdot\vec{n}} = \cos\psi\hat{I} - i\sin\psi(\vec{\sigma}\cdot\vec{n})$

$$\Rightarrow \begin{pmatrix} \tilde{C}_a(t) \\ \tilde{C}_b(t) \end{pmatrix} = \begin{pmatrix} \cos\frac{\omega_r}{2}t + i\frac{\delta}{\omega_r}\sin\frac{\omega_r}{2}t & -i\frac{2V_{ab}}{\hbar\omega_r}\sin\frac{\omega_r}{2}t \\ i\frac{2V_{ab}}{\hbar\omega_r}\sin\frac{\omega_r}{2}t & \cos\frac{\omega_r}{2}t - i\frac{\delta}{\omega_r}\sin\frac{\omega_r}{2}t \end{pmatrix} \begin{pmatrix} \tilde{C}_a(0) \\ \tilde{C}_b(0) \end{pmatrix}$$

$(\omega_r = \sqrt{\delta^2 + \frac{4|V_{ab}|^2}{\hbar^2}})$ 如 $\begin{cases} \tilde{C}_a(0) = 1 \\ \tilde{C}_b(0) = 0 \end{cases} \Rightarrow \tilde{C}_a(t) = \cos\frac{\omega_r}{2}t + i\frac{\delta}{\omega_r}\sin\frac{\omega_r}{2}t \rightarrow$ Rabi 振荡 最早 $t = \frac{2\pi}{\omega_r}$ 时 $|\tilde{C}_a(t)|^2 = 1$.



$|\delta| \gg |V_{ab}| \rightarrow$ 两能级近似很正确, 之上的能级离基态太远, 不会有太多耦合

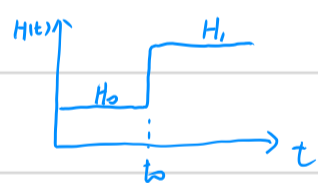
1. 含时问题的特例

① 常微扰



初态 $|n\rangle$, 末态 $|m\rangle$
修正: $\tilde{C}_m^{(1)}(t) = -\frac{i}{\hbar} \int_0^t V_{mn} e^{i\omega_{mn}t'} dt'$ ✓

② 突变近似

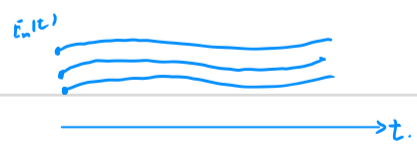


在 t_0 时刻 H 突变, 态近似不变 $\begin{cases} \hat{H}_0 |n\rangle = E_n |n\rangle \\ \hat{H}_1 |n_0\rangle = E_0 |n_0\rangle \end{cases}$

$0 < t < t_0: |\psi\rangle = \sum_n C_n e^{-i\frac{E_n t}{\hbar}} |n\rangle \quad t > t_0: |\psi\rangle = \sum_n C_n e^{-i\frac{E_n t_0}{\hbar}} \sum_n \langle n_0 | n \rangle |n_0\rangle e^{-i\frac{E_0 (t-t_0)}{\hbar}}$

③ 绝热近似

$H(t)$ 缓变, 则初始本征态绝热跟随当前 $H(t)$ 的本征态演化



$t > 0: |k(t)\rangle \approx e^{i\theta_k(t)} e^{i\gamma_k(t)} |k_n(t)\rangle$
 \downarrow 动力学相位 \downarrow 几何相位

$\theta_n = -\frac{1}{\hbar} \int_0^t E_n(t') dt'$
 $\gamma_n = i \int_0^t \langle k_n(t') | \frac{\partial}{\partial t'} |k_n(t')\rangle dt'$

绝热条件: $\omega \gg \dot{\epsilon}$